

Efficient simulation of Grassmann Tensor Product States

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Recently, the Grassmann-tensor-entanglement renormalization group(GTERG) approach was proposed as a generic variational approach to study strongly correlated boson/fermion systems¹. However, the weakness of such a simple variational approach is that generic Grassmann tensor product states(GTPS) with large inner dimension D will contain a large number of variational parameters and be hard to be determined through usual minimization procedures. In this paper, we first introduce a standard form of GTPS which significantly simplifies the representations. Then we describe a simple imaginary-time-evolution algorithm to efficiently update the GTPS based on the fermion coherent state representation and show all the algorithm developed for usual tensor product states(TPS) can be implemented for GTPS in a similar way. Finally, we study the environment effect for the GTERG approach and propose a simple method to further improve its accuracy. We demonstrate our algorithms by studying a simple 2D free fermion system on honeycomb lattice, including both off-critical and critical cases.

Keywords:

I. INTRODUCTION

Since the discovery of fractional quantum hall effect(FQHE) and high T_c cuprates, it has been realized that a large class of phases and phase transitions can not be described by Landau symmetry breaking theory. Enormous efforts have been made to understand the underlying physics for these new systems during the last two decades. It has been realized that the strongly correlated nature plays an essential role for these new classes of quantum matter. The most successful and powerful approach to study these new systems is based on new classes of variational wave functions. For example, the famous Laughlin wave function² successfully explains the quantized nature of Hall conductance at rational filling. It turns out such a new state is very different from a symmetry breaking state and it can describe new orders of quantum matter—topological order³. Although the essential physics of high- T_c is still under controversial, it is believed the relevant low energy physics is controlled by a class of metastable states—the resonating-valence-bond(RVB) states^{4,6}. A quantitative description for the RVB states is based on the projective wave function approach, which was first proposed to satisfy the no-double-occupancy constraint for (repulsive)Hubbard model in the strong coupling limit^{5,6}. It turns out this new class of states can also describe new phases of matter with topological order or quantum order⁷. Later, those projective functions are widely used to describe the novel phenomena in strongly correlated systems, including frustrated magnets⁸ as well as the lattice fractional quantum hall states⁹.

Despite the success of projective states, they are specially designed to describe states with particular topological order or quantum order and it is very difficult to study the competing effect between different orders. Thus, it is very important to establish a unified framework to encode different orders of quantum matter. In

Ref.¹, a natural generalization of the projective states, the Grassmann tensor product states(GTPS) have been proposed as generic variational wave functions to study interacting boson/fermion systems.

However, only local GTPS(GTPS with short range bonds)can be efficiently simulated approximately¹. As a result, it is also very important to understand what kind of states can be faithfully represented in a local way. For spin systems, Refs.^{10,11} have shown that the ground states of non-chiral topological phases, the so called string-net condensates¹², admit a local tensor product states(TPS) representation. Later, the fermionic version of string-net states was proposed in Ref.¹³ and it has been shown they can describe non-chiral topological orders(e.g., fractional topological insulators) in fermion systems. Similar as the bosonic string-net states, their ground states can also be faithfully represented as GTPS since the parent Hamiltonians for these new classes of phases can be described as summations of (fermionic)commuting projectors. In a recent work, it has been shown even for systems with chiral topological orders, all the physical quantities still admit a local GTPS representation¹⁴ despite that their ground states wave functions contain long range bonds^{1,15}. Thus, best to our knowledge, the GTPS variational approach can in principle describe all kinds of gapped local boson/fermion systems in 1+2D. Clearly, the advantage of this new variational approach is that it provides a unified description for many different orders of quantum matter and allows us to study the competing effect between these different orders.

On the other hand, from the quantum information and computation perspective, it has been shown that ground states of gapped local Hamiltonians obey so-called area laws. For local boson/spin systems with translational invariant, states satisfy such a property can be efficiently represented by the class of so-called matrix product states(MPS) in one dimension and tensor

product states(TPS) or projected entangled pair states (PEPS) in higher dimensions^{16,17}. Recently, a fermionic generalization of those states—the fermionic projected entangled pair states (fPEPS) were proposed and have been bench marked for many interesting free/interacting fermion systems^{18–24}. In Ref.¹, it has been shown all fPEPS can be represented as (local)GTPS.

Although GTPS are conceptually useful, the implementations in generic strongly correlated boson/fermion systems are still not easy since the tensor contraction for generic GTPS is an exponential hard problem. Similar difficulties occur for PEPS(fPEPS)²⁵ and many efforts have been made based on the MPS algorithm^{26–28}. However, the MPS algorithm still has a very big cost to handle large system with periodical boundary condition(PBC)²⁶. Alternatively, based on the concept of renormalization²⁹, the so-called tensor-entanglement renormalization group(GTERG)^{30,31} method and its recent development^{32–34} turn out to be very successful for systems with PBC. Similar as TERG, based on the renormalization principle for Grassmann variables, the Grassmann-tensor-entanglement renormalization group(GTERG) was proposed in Ref.¹ to simulate physical measurements for GTPS approximately. However, a naive minimization procedure for generic GTPS variational approach will still be very hard due to the large number of variational parameters when inner dimension D increases(scale as D^3 on honeycomb lattice and D^4 on square lattice). For TPS, it is well known the imaginary time evolution algorithm is the best method to solve this problem. Thus, it is natural to generalize this algorithm into GTPS.

In this paper, we will show based on the fermion coherent state representation, all the algorithms developed for usual TPS can be easily generalized into GTPS. The paper is organized as following: In section II, we represent a standard form of GTPS, which only contains one specie of Grassmann variable for each inner index and significantly simplifies the representation for numerical calculations. In section III, we first give a brief review about the concept of imaginary time evolution algorithm for TPS and then present the detail implementation of the imaginary time evolution algorithm for GTPS. Finally, we demonstrate the algorithm for a simple spinless fermion system on honeycomb lattice, including both off-critical and critical cases. In section IV, we describe the environment effect of the GTERG algorithm and present a simple improved algorithm. We implement the algorithm for a critical free fermion system on honeycomb lattice and find a significant improvement. Finally, we briefly summarize our results and discuss possible future developments along this direction.

II. STANDARD FORM FOR GTPS

In this section, we will introduce a standard form to represent GTPS. In the standard form, each link only

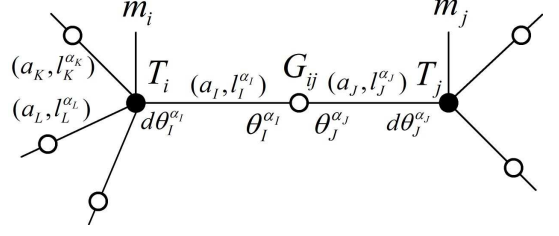


FIG. 1: A Graphic representation for the GTPS. The open circle which connects to links I and J represents the Grassmann metric $G_{ij,a_I a_J}$. The filled circle on the physical site i represents the Grassmann tensors $T_{i;a_K a_L \dots}^{m_i}$. the Grassmann numbers θ_I^α associate with the Grassmann metric $G_{ij,a_I a_J}$ and the dual Grassmann numbers associate with the Grassmann tensor $T_{i;a_K a_L \dots}^{m_i}$. There are a pair of indices $(a_I, \{l_I^\alpha\})$ live on link I . a_I is called the bosonic index while $\{l_I^\alpha\} = 0, 1$ are called the fermionic indices.

associates with one Grassmann variable, thus, the representation in the numerical calculations will be simplified significantly.

Let us recall the generic GTPS wavefunctions(defined in the usual Fork basis):

$$\Psi(\{m_i\}) = \sum_{\{a_I\}} P_0 \int \prod_i T_{i;a_K a_L \dots}^{m_i} \prod_{ij} G_{ij,a_I a_J}, \quad (1)$$

where

$$\begin{aligned} T_{i;a_K a_L \dots}^{m_i} &= \sum_{\{l_K^{\alpha_K}\} \{l_L^{\alpha_L}\} \dots} T_{i;a_K a_L \dots}^{m_i; \{l_K^{\alpha_K}\} \{l_L^{\alpha_L}\} \dots} \prod_{I \in i} \prod_{\alpha_I} (d\theta_I^{\alpha_I})^{l_I^{\alpha_I}} \\ G_{ij,a_I a_J} &= \sum_{\{l_I^{\alpha_I}\} \{l_J^{\alpha_J}\}} G_{ij,a_I a_J}^{\{l_I^{\alpha_I}\} \{l_J^{\alpha_J}\}} \prod_{\alpha_J} (\theta_J^{\alpha_J})^{l_J^{\alpha_J}} \prod_{\alpha_I} (\theta_I^{\alpha_I})^{l_I^{\alpha_I}} \end{aligned} \quad (2)$$

Here i, j, \dots label different physical sites, I, J, \dots label different links and $I \in i$ means the link I connects to the site i (See in Fig. 1, any link I uniquely belongs to one physical site i). On each link I , a_I label the bosonic inner indices, $l_I^\alpha = 0, 1$ label the fermionic inner indices and α_I label different species of Grassmann variables. m_i is the physical index. $\theta_I^{\alpha_I}$ and $d\theta_I^{\alpha_I}$ are Grassmann numbers and dual Grassmann numbers that satisfy the standard Grassmann algebra:

$$\begin{aligned} \theta_I^{\alpha_I} \theta_{I'}^{\alpha_{I'}} &= -\theta_{I'}^{\alpha_{I'}} \theta_I^{\alpha_I}, \quad d\theta_I^{\alpha_I} d\theta_{I'}^{\alpha_{I'}} = -d\theta_{I'}^{\alpha_{I'}} d\theta_I^{\alpha_I}, \\ \int d\theta_I^{\alpha_I} \theta_{I'}^{\alpha_{I'}} &= \delta_{I,I'} \delta_{\alpha_I, \alpha_{I'}}, \quad \int d\theta_I^{\alpha_I} 1 = 0. \end{aligned} \quad (3)$$

Note that \prod_i and $\widetilde{\prod}_i$ have opposite orders:

$$\prod_i \theta_i \equiv \theta_1 \theta_2 \theta_3 \dots \quad \widetilde{\prod}_i \theta_i \equiv \dots \theta_3 \theta_2 \theta_1. \quad (4)$$

The symbol P_0 represents a projection of the result of the integral to the term containing no Grassmann variables $\theta_I^{\alpha_I}$.

For fermion(electron) systems, the physical indices m_i on a local Hilbert space are always associated with a definite fermion parity $P_f(m_i) = \pm 1$. Hence, we can impose the following constraints to issue that Eq. (38) do represent fermion wavefunctions.

$$\begin{aligned} \sum_{I \in i} \sum_{\alpha_I} l_I^{\alpha_I} &= \text{odd, if } P_f(m_i) = -1 \\ \sum_{I \in i} \sum_{\alpha_I} l_I^{\alpha_I} &= \text{even, if } P_f(m_i) = 1 \\ \sum_{\alpha_I} l_I^{\alpha_I} + \sum_{\alpha_J} l_J^{\alpha_J} &= \text{even} \end{aligned} \quad (5)$$

Although the original form Eq.(38) provides us a good physical insight of the state, especially for strongly correlated systems from projective constructions, it is not an efficient representation for numerical simulations. In the following we will derive the standard form of GTPS to simplify the representation.

By using the Grassmann version of singular-value-decomposition(GSVD) method proposed in Ref.¹, under the constraint $\sum_{\alpha_I} l_I^{\alpha_I} + \sum_{\alpha_J} l_J^{\alpha_J} = \text{even}$, we can decompose $G_{ij; a_I a_J}$ into:

$$G_{ij; a_I a_J} = \sum_{p_I p_J} P'_0 \int g_{ij; q_I q_J} S_{I; a_I q_I} S_{J; a_J q_J} \quad (6)$$

with

$$\begin{aligned} g_{ij; q_I q_J} &= (1 + d\theta_J d\theta_I) \delta_{q_I q_J} \\ S_{I; a_I q_I} &= \sum_{\{l_I^{\alpha_I}\}_{n_I}} S_{I; a_I q_I}^{\{l_I^{\alpha_I}\}_{n_I}} \left[\prod_{\alpha_I} (\theta_I^{\alpha_I})^{l_I^{\alpha_I}} \right] \theta_I^{n_I} \\ S_{J; a_J q_J} &= \sum_{\{l_J^{\alpha_J}\}_{n_J}} S_{J; a_J q_J}^{\{l_J^{\alpha_J}\}_{n_J}} \left[\prod_{\alpha_J} (\theta_J^{\alpha_J})^{l_J^{\alpha_J}} \right] \theta_J^{n_J} \end{aligned} \quad (7)$$

and

$$n_I = n_J = \sum_{\alpha_I} l_I^{\alpha_I} \bmod 2 = \sum_{\alpha_J} l_J^{\alpha_J} \bmod 2, \quad (8)$$

where $S_{I; a_I q_I}^{\{l_I^{\alpha_I}\}_{n_I}} = \sqrt{\Lambda_{q_I, n_I}} U_{a_I \{l_I^{\alpha_I}\}_{q_I, n_I}}$ and $S_{J; a_J q_J}^{\{l_J^{\alpha_J}\}_{n_J}} = \sqrt{\Lambda_{q_J, n_J}} V_{a_J \{l_J^{\alpha_J}\}_{q_J, n_J}}$ are determined by the singular-value-decomposition(SVD) for the matrix $M_{a_I \{l_I^{\alpha_I}\}_{a_J \{l_J^{\alpha_J}\}}} = G_{ij; a_I a_J}^{\{l_I^{\alpha_I}\}_{n_I} \{l_J^{\alpha_J}\}_{n_J}}$ with $M = U \Lambda V^T$. (Notice the the constraint $\sum_{\alpha_I} l_I^{\alpha_I} + \sum_{\alpha_J} l_J^{\alpha_J} = \text{even}$ implies a Z_2 symmetry for the matrix M and it can be block diagonalized, with each sector labeled as $n_I = n_J = 0$ or 1 .) Again, the symbol P'_0 represents a projection of the result of the integral to the term containing no Grassmann number θ_I . We call $g_{ij; q_I q_J}$ the standard metric for GTPS, which is the Grassmann generalization of the canonical delta function $\delta_{q_I q_J}$.

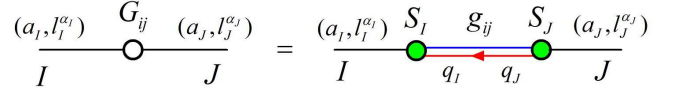


FIG. 2: A graphic representation of the decomposition Eq. (6). We use double lines (red and blue) to represent the standard metric g_{ij} , which is the Z_2 graded version of the canonical delta function. The blue line represents the channel with no inner fermion ($n_I = n_J = 0$) and the red line represents the channel with one inner fermion ($n_I = n_J = 1$) for the standard metric. The arrow of the red line represents the ordering for the dual Grassmann variables $d\theta_I$ and $d\theta_J$. We notice the standard metric g_{ij} only has one specie of Grassmann variable despite the original Grassmann metric G_{ij} contains many species of Grassmann variables on its link I and J (labeled by α_I and α_J). Here q_I, q_J and a_I, a_J are bosonic indices.

Put Eq.(6) into Eq.(38), we have:

$$\begin{aligned} \Psi(\{m_i\}) &= \sum_{\{a_I\}, \{q_I\}} P_0 P'_0 \int \prod_{ij} g_{ij; q_I q_J} \\ &\times \prod_i T_{i; a_K a_L \dots}^{m_i} \prod_I S_{I; a_I q_I}, \end{aligned} \quad (9)$$

The Grassmann matrices $S_{I; a_I q_I}$ defined on all links contain even number of Grassmann numbers and they commute with each other. Such a property allows us to re-group them as:

$$\prod_I S_{I; a_I q_I} = \prod_i \widetilde{\prod_{I \in i}} S_{I; a_I q_I}, \quad (10)$$

We use the fact that each link I uniquely belongs to a site i to derive the above expression. We note $\widetilde{\prod}$ defined here have opposite orders according to \prod defined in Eq. (2)

Thus, we can integral out all the Grassmann numbers $\prod_{\alpha_I} (\theta_I^{\alpha_I})^{l_I^{\alpha_I}}$ and sum over all the bosonic indices $\{a_I\}$ to derive a simplified wave function:

$$\Psi(\{m_i\}) = \sum_{\{q_I\}} P'_0 \int \prod_{ij} g_{ij; q_I q_J} \prod_i \widetilde{T}_{i; q_K q_L \dots}^{m_i}, \quad (11)$$

where the new Grassmann tensor $\widetilde{T}_{i; q_K q_L \dots}^{m_i}$ associate with physical site i can be expressed as:

$$\widetilde{T}_{i; q_K q_L \dots}^{m_i} = \sum_{n_K n_L \dots} \widetilde{T}_{i; q_K q_L \dots}^{m_i; n_K n_L \dots} \prod_{I \in i} \theta_I^{n_I} \quad (12)$$

with

$$\begin{aligned} \widetilde{T}_{i; q_K q_L \dots}^{m_i; n_K n_L \dots} &= \sum_{a_K a_L \dots} \sum_{\{l_K^{\alpha_K}\} \{l_L^{\alpha_L}\} \dots} \prod_{I \in i} S_{I; a_I q_I}^{\{l_I^{\alpha_I}\}_{n_I}} \\ &\times T_{i; a_K a_L \dots}^{m_i; \{l_K^{\alpha_K}\} \{l_L^{\alpha_L}\} \dots} \end{aligned} \quad (13)$$

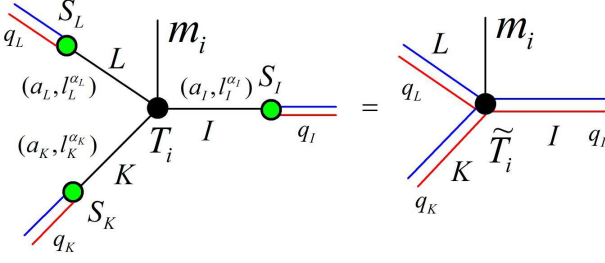


FIG. 3: A Graphic representation for the standard Grassmann tensor \tilde{T}_i , which is a combination of the Grassmann tensor T_i and those $S_{I(K,L)}$ (green solid circles) surrounding it.

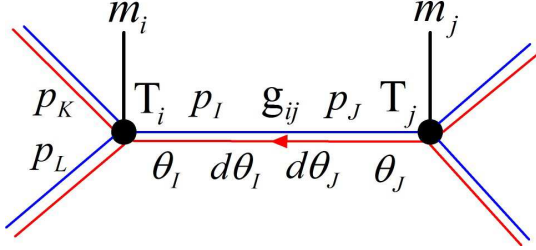


FIG. 4: A graphic representation for the standard form of GTPS. The filled circle on the physical site i represents the standard Grassmann tensors $\mathbf{T}_{i;p_K p_L \dots}^{m_i}$. The link index p_I has a definite fermion parity P_f and we use blue(red) line to represent the fermion parity even(odd) $P_f(p_I) = 1(-1)$ indices. If $P_f(p_I) = -1$, we associate a Grassmann number θ_I with the standard Grassmann tensor $\mathbf{T}_{i;p_K p_L \dots}^{m_i}$ while associate its dual $d\theta_I$ with the standard metric $\mathbf{g}_{ij;p_I p_J}$. Since the standard metric $\mathbf{g}_{ij;p_I p_J}$ is actually just a Grassmann generalization of the canonical delta function $\delta_{p_I p_J}$, we only need to use an arrow to specify the ordering of the two Grassmann variables $d\theta_J$ and $d\theta_I$.

We call Eq.(11) the standard form of GTPS which only contains one specie of Grassmann variable on each link. We can further simplify the expression by group the bosonic index q_I and fermionic index n_I into one super index $p_I = (q_I, n_I)$.

$$\Psi(\{m_i\}) = \sum_{\{p_I\}} \int \prod_{ij} \mathbf{g}_{ij;p_I p_J} \prod_i \mathbf{T}_{i;p_K p_L \dots}^{m_i}, \quad (14)$$

with

$$\begin{aligned} \mathbf{g}_{ij;p_I p_J} &= \delta_{p_I p_J} (d\theta_J)^{N_f(p_J)} (d\theta_I)^{N_f(p_I)} \\ \mathbf{T}_{i;p_K p_L \dots}^{m_i} &= \tilde{\mathbf{T}}_{i;q_K q_L \dots}^{m_i; n_K n_L \dots} \prod_{I \in i} (\theta_I)^{N_f(p_I)}, \end{aligned} \quad (15)$$

where $N_f(p_I) = n_I$. Notice the super index p_I has a definite fermion parity $P_f(p_I) = \pm 1$ and the corresponding fermion number is determined as $N_f = \frac{P_f + 1}{2}$.

The new form Eq.(14) is extremely useful in general

purpose of numerical calculations. We will use this new form to explain all the details of our algorithms.

III. THE IMAGINARY TIME EVOLUTION ALGORITHM

In this section, we will give a brief review of imaginary time evolution algorithm of usual TPS first and then generalize all those algorithms into GTPS. Finally, we apply the algorithms to a simple free fermion example on honeycomb lattice.

A. A review of the algorithm of TPS

1. generic discussion

Let us consider the imaginary time evolution for generic TPS $|\Psi_0\rangle$.

$$|\Psi_\tau\rangle = e^{-\tau H} |\Psi_0\rangle \quad (16)$$

If we don't make any approximation, the true ground state can be achieved in the $\tau \rightarrow \infty$ limit.

$$|\Psi_{GS}\rangle = \lim_{\tau \rightarrow \infty} e^{-\tau H} |\Psi_0\rangle = \lim_{N \rightarrow \infty} e^{-N \delta\tau H} |\Psi_0\rangle, \quad (17)$$

where N is the number of evolution steps and $\delta\tau = \tau/N$ is a sufficiently thin imaginary-time slice. However, without any approximation, the inner dimension of TPS will increase exponentially with the number of evolution steps. Hence, we need to find out the best TPS approximation with fixed inner dimension.

WLOG, we use the honeycomb lattice geometry to explain the details here and for the rest parts of the paper. To illustrate the key idea of the algorithm, let us consider a simple case that the model Hamiltonian H only contains a summation of nearest neighbor two-body terms:

$$H = \sum_{\langle ij \rangle} h_{ij}. \quad (18)$$

Let us divide the Hamiltonian into three parts:

$$H = H_x + H_y + H_z; \quad H_\alpha = \sum_{i \in A} h_{i, i+\alpha} \quad (\alpha = x, y, z), \quad (19)$$

where A label the sublattices A and x, y, z label three different nearest neighbor directions. By applying the Trotter expansion, we have:

$$e^{-\delta\tau H} = e^{-\delta\tau H_x} e^{-\delta\tau H_y} e^{-\delta\tau H_z} + o(\delta\tau^2) \quad (20)$$

Notice each H_α only contains summation of commuting terms, hence we can decompose them without errors:

$$e^{-\delta\tau H_\alpha} = \prod_i e^{-\delta\tau h_{i, i+\alpha}} \quad (21)$$

Let us expand $|\Psi_0\rangle$ under the physical basis:

$$|\Psi_0\rangle = \sum_{\{m_i, m_j\}} \sum_{\{a, a'\}} \prod_{i \in A} T_{i;abc}^{m_i} \prod_{j \in B} T_{j;a'b'c'}^{m_j} \prod_{ij} \delta_{aa'} |\{m_i, m_j\}\rangle, \quad (22)$$

Here A, B denote two different sublattice in a unit cell and $m_{i(j)}$ denote the physical indices on site $i(j)$, e.g., $m_{i(j)} = \uparrow, \downarrow$ for a spin 1/2 system. The canonical delta function $\delta_{aa'}$ defined on link ij can be regarded as the metric associated with tensor contraction, which can be generalized to its Grassmann variable version for fermion systems. After acting one evolution operator $e^{-\delta\tau h_{ij}}$ onto the corresponding link ij , we can expand the new state $e^{-\delta\tau h_{ij}}|\Psi_0\rangle$ as:

$$e^{-\delta\tau h_{ij}}|\Psi_0\rangle = \sum_{\{m_i, m_j\}} \sum_{\{a, a'\}} \sum_{m'_i m'_j} E_{m'_i m'_j}^{m_i m_j} T_{i;abc}^{m'_i} T_{j;a'b'c'}^{m'_j} \times \prod_{i' \neq i} T_{i';edf}^{m_{i'}} \prod_{j' \neq j} T_{j';e'd'f'}^{m_{j'}} \prod_{ij} \delta_{aa'} |\{m_i, m_j\}\rangle \quad (23)$$

where $E_{m'_i m'_j}^{m_i m_j} = \langle m_i m_j | e^{-\delta\tau h_{ij}} | m'_i m'_j \rangle$ is the matrix element of the evolution operator on link ij . Use the SVD decomposition, we can decompose the rank 6 tensor $T_{ij; m_i m_j bcb'c'} = \sum_a \sum_{m'_i m'_j} E_{m'_i m'_j}^{m_i m_j} T_{i;abc}^{m'_i} T_{j;a'b'c'}^{m'_j}$ as:

$$T_{ij; m_i m_j bcb'c'} = \sum_{aa'} \mathcal{T}_{i;abc}^{m_i} \mathcal{T}_{j;a'b'c'}^{m_j} \delta_{aa'}. \quad (24)$$

Here the indices a, a' have dimension Dd^2 , where D is the inner dimension and d is the physical dimension of the tensor $T_{i;abc}^{m_i}$. After applying $e^{-\delta\tau H_x}$ on state $|\Psi_0\rangle$, the tensor T_i will be replaced by \mathcal{T}_i :

$$e^{-\delta\tau H_x}|\Psi_0\rangle = \sum_{\{m_i, m_j\}} \sum_{\{a, a'\}} \prod_{i \in A} \mathcal{T}_{i;abc}^{m_i} \prod_{j \in B} \mathcal{T}_{j;a'b'c'}^{m_j} \prod_{ij} \delta_{aa'} |\{m_i, m_j\}\rangle, \quad (25)$$

Notice all $\{\mathcal{T}_{i;abc}^{m_i}\}$ have enlarged inner dimension Dd^2 instead of D for their inner indices a (the bond along x direction). Similarly, the dimension of indices b, c (the bonds along y, z directions) will also be enlarged to Dd^2 after applying $e^{-\delta\tau H_y}$ and $e^{-\delta\tau H_z}$ on $|\Psi_0\rangle$. Thus, it is easy to see that the inner dimension will increase exponentially with increasing evolution steps if we don't make any truncation.

To solve the above difficulty, we need to find a new set of $\{T_{i;abc}^{m_i}\}$ with fixed inner dimension D that minimizes the distance with $e^{-\delta\tau H_x}|\Psi_0\rangle$. If we start from $|\Psi_0\rangle$ and evolve it by $e^{-\delta\tau H_x}$ in a sufficient thin time slice, the cost function f takes the form:

$$f(\{T_{i;abc}^{m_i}\}) = |||\Psi_0'\rangle - e^{-\delta\tau H_x}|\Psi_0\rangle|| = \langle \Psi_0' | \Psi_0' \rangle - (\langle \Psi_0' | e^{-\delta\tau H_x} | \Psi_0 \rangle + h.c.) + const., \quad (26)$$

where

$$|\Psi_0'\rangle = \sum_{\{m_i, m_j\}} \sum_{\{a, a'\}} \prod_{i \in A} T_{i;abc}^{m_i} \prod_{j \in B} T_{j;a'b'c'}^{m_j} \prod_{ij} \delta_{aa'} |\{m_i, m_j\}\rangle, \quad (27)$$

f is a multi-variable quadratic function of $\{T_{i;abc}^{m_i}\}$, hence we can use the sweep method to minimize it. The advantage of the above algorithm is that the Trotter error will not accumulate after long time evolution. However, calculating the cost function f explicitly is an exponentially hard problem and we need further approximations at this stage. Some possible methods have been proposed based on the MPS algorithm²⁶, but the calculational cost can still be very large and the method has only been implemented with open boundary condition(OBC) so far.

2. translational invariant systems

Nevertheless, for translational invariant TPS ansatz, it is possible to develop efficient method to simulate the cost function by using the TERG method. We assume $T_i = T_A$ if $i \in A$ and $T_j = T_B$ if $j \in B$. The cost function can be expressed as:

$$f(T'_A, T'_B) = \rho^{bcb'c'; \bar{b}\bar{c}\bar{b}'\bar{c}'} \bar{T}_A^{m_i} T_{A;abc}^{m_i} \bar{T}_B^{m_j} T_{B;\bar{a}\bar{b}'\bar{c}'}^{m_j} T_{B;ab'c'}^{m_j} - \left(e^{\bar{b}\bar{c}\bar{b}'\bar{c}'; m_i m_j} \bar{T}_A^{m_i} \bar{T}_B^{m_j} T_{B;\bar{a}\bar{b}'\bar{c}'}^{m_j} + h.c. \right) + const, \quad (28)$$

where ρ and e (Fig. 5) are the so called environment tensors. Here we use the convention that all the repeated indices will be summed over and use \bar{T} to represent complex conjugate of T . Strictly speaking, the environment tensors for ρ and e are also dependent on T'_A and T'_B , thus f is no longer a quadratic multi-variable function. However, for sufficiently thin time slice, up to $o(\delta\tau^2)$ error (same order as Trotter error), we can replace T'_A, T'_B by T_A, T_B when calculating the environment tensor ρ . e can be derived from ρ :

$$e^{\bar{b}\bar{c}\bar{b}'\bar{c}'; m_i m_j} = \rho^{bcb'c'; \bar{b}\bar{c}\bar{b}'\bar{c}'} E_{m'_i m'_j}^{m_i m_j} T_{A;abc}^{m'_i} T_{B;ab'c'}^{m'_j} \quad (29)$$

Again, repeated indices need to be summed over here. We notice ρ can be expressed as a tensor trace of double tensors $\mathbb{T}_{A(B)} = \sum_m \bar{T}_{A(B)}^m \otimes T_{A(B)}^m$ with an impurity tensor \mathbb{T}_{ij} sites on the link ij :

$$\rho^{bcb'c'; \bar{b}\bar{c}\bar{b}'\bar{c}'} = \text{tTr}[\mathbb{T}_{ij}^\rho \otimes \mathbb{T}_A \otimes \mathbb{T}_B \otimes \mathbb{T}_A \otimes \mathbb{T}_B \cdots], \quad (30)$$

where the impurity double tensor \mathbb{T}_{ij} is just a projector:

$$\mathbb{T}_{ij; bcb'c'; \bar{b}\bar{c}\bar{b}'\bar{c}'} = 1; \quad \text{others} = 0 \quad (31)$$

Now it is easy to see we can first decompose the impurity tensor on the link i, j to two rank 3 impurity tensors on

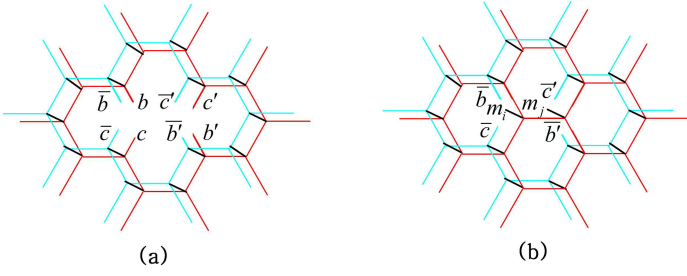


FIG. 5: A graphic representation for the environment tensor ρ ((a)) and e ((b)) on honeycomb lattice.

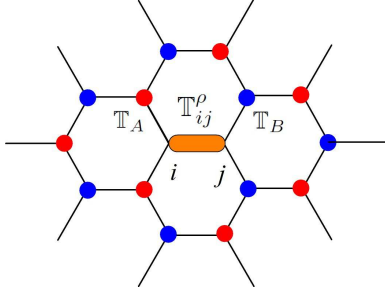


FIG. 6: A graphic representation for the tensor contraction that allow us to compute ρ on honeycomb lattice.

site i, j and then implement the usual TERC algorithm. We can also use a more efficient but complicated way to compute ρ by applying the coarse grain procedures for all sites except sites i, j , as introduced in Ref.³².

The above algorithm can be further simplified if we assume the environment tensor ρ has specific forms for certain physical systems. One interesting attempting is proposed in Ref.³¹ by assuming ρ can be factorized as:

$$\rho^{bcb'c';\bar{b}\bar{c}\bar{b}'\bar{c}'} = \Lambda_b^y \Lambda_c^z \Lambda_{b'}^y \Lambda_{c'}^z \delta_{b\bar{b}} \delta_{c\bar{c}} \delta_{b'\bar{b}'} \delta_{c'\bar{c}'}, \quad (32)$$

where Λ^α is a positive weight vector defined on links along α direction. The above form can always be true for 1D systems³⁵ due to the existence of canonical form of a MPS. Although the above form is not generic enough in 2D, it still works well in many cases, especially for those systems with symmetry breaking order. In this case, the cost function Eq.(28) can be solved by SVD decomposition and keep the leading D singular values for

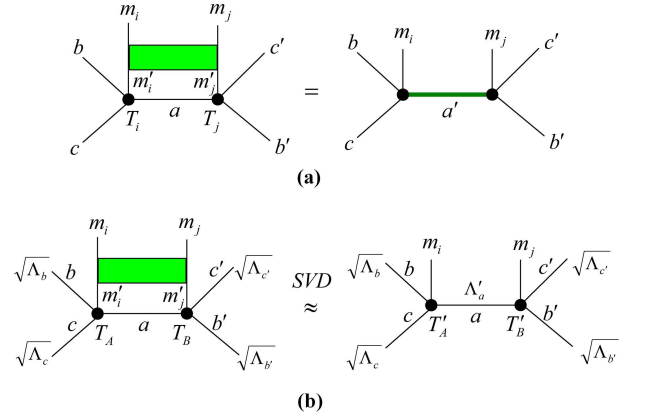


FIG. 7: (a) After applying the two body evolution operator $e^{-\delta\tau h_{ij}}$ to the ij link for TPS (with inner dimension D), we get new TPS with enlarged inner dimension (Dd^2 , d is the physical dimension) for the corresponding link. (b) For large classes of translational invariant TPS, we can reduce the inner dimension from Dd^2 back to D with respect to some environment weight Λ .

the following matrix:

$$\begin{aligned} M_{bcm_i;b'c'm_j} &= \sum_{a,m'_i,m'_j} \sqrt{\Lambda_b^y} \sqrt{\Lambda_c^z} \sqrt{\Lambda_{b'}^y} \sqrt{\Lambda_{c'}^z} T_{ij,m_i n_j bcb'c'} \\ &= \sum_{a,m'_i,m'_j} \sqrt{\Lambda_b^y} \sqrt{\Lambda_c^z} \sqrt{\Lambda_{b'}^y} \sqrt{\Lambda_{c'}^z} \\ &\quad \times E_{m'_i m'_j}^{m_i m_j} T_{A;abc}^{m'_i} T_{B;ab'c'}^{m'_j} \\ &\simeq \sum_{a=1}^D U_{bcm_i;a} V_{b'c'm_j;a} \Lambda'_a \end{aligned} \quad (33)$$

The new tensors T'_A and T'_B can be determined as:

$$\begin{aligned} T'^{m_i}_{A;abc} &= \frac{\sqrt{\Lambda'_a}}{\sqrt{\Lambda_b^y} \sqrt{\Lambda_c^z}} U_{bcm_i;a} \\ T'^{m_j}_{B;a'b'c'} &= \frac{\sqrt{\Lambda'_a}}{\sqrt{\Lambda_{b'}^y} \sqrt{\Lambda_{c'}^z}} V_{b'c'm_j;a'} \end{aligned} \quad (34)$$

Similar as in 1D, the environment weight associated with bonds along x direction is updated as $\Lambda^x = \Lambda'$. It is not hard to understand why the above simplified algorithm works very well for systems with symmetry breaking orders, but not in the critical region, since in those cases the ground states are close to product states and the entanglements between x, y, z directions in the environment tensors become pretty weak. However, for topological ordered states, the environment tensors can be more complicated. For example, the Z_2 topological ordered state in the toric code model will have an emergent Z_2 symmetry and could not be factorized as a product. Hence, for topological ordered states, it is important to calculate the full environment in the imaginary time evolution.

B. Generalize to fermion(electron) systems

In this subsection, we will show how to generalize the above algorithms to GTPS. The key step is to introduce fermion coherent state representation and treat the physical indices also as a Grassmann variable. WLOG, we use a spinless fermion system as a simple example here and for the rest parts of the paper:

$$|\eta\rangle \equiv \prod_i (1 - \eta_i c_i^\dagger) |0\rangle, \quad (35)$$

where η_i is a Grassmann number.

As already having been discussed in Ref.¹, in this new basis, the GTPS wavefunction Eq.(38) and its standard form Eq.(14) can be represented as:

$$\begin{aligned} \Psi(\{\eta_i\}) &= \sum_{\{m_i\}} \sum_{\{a_I\}} \int \prod_i \bar{\eta}_i^{m_i} T_{i;a_K a_L \dots}^{m_i} \prod_{ij} G_{ij;a_I a_J} \\ &= \sum_{\{m_i\}} \sum_{\{p_I\}} \int \prod_{ij} \mathbf{g}_{ij;p_I p_J} \prod_i \bar{\eta}_i^{m_i} \mathbf{T}_{i;p_K p_L \dots}^{m_i} \\ &= \sum_{\{m_i\}} \sum_{\{p_I\}} \int \prod_{ij} \mathbf{g}_{ij;p_I p_J} \prod_i \tilde{\mathbf{T}}_{i;p_K p_L \dots}^{m_i} \end{aligned} \quad (36)$$

where $\bar{\eta}_i$ is the complex conjugate of the Grassmann number η_i and $\tilde{\mathbf{T}}_{i;p_K p_L \dots}^{m_i} = \bar{\eta}_i^{m_i} \mathbf{T}_{i;p_K p_L \dots}^{m_i}$.

On honeycomb lattice with translational invariant, we can simplify the above expression as:

$$\begin{aligned} \Psi(\{\bar{\eta}_i\}, \{\bar{\eta}_j\}) &= \sum_{\{m_i\}, \{m_j\}} \sum_{\{a\}, \{a'\}} \int \prod_{\langle ij \rangle} \mathbf{g}_{aa'} \prod_{i \in A} \tilde{\mathbf{T}}_{A;abc}^{m_i} \prod_{j \in B} \tilde{\mathbf{T}}_{B;a'b'c'}^{m_j}, \end{aligned} \quad (37)$$

with

$$\begin{aligned} \tilde{\mathbf{T}}_{A;abc}^{m_i} &= \tilde{\mathbf{T}}_{A;abc}^{m_i} \bar{\eta}_i^{m_i} \theta_\alpha^{N_f(a)} \theta_\beta^{N_f(b)} \theta_\gamma^{N_f(c)}, \\ \tilde{\mathbf{T}}_{B;a'b'c'}^{m_j} &= \tilde{\mathbf{T}}_{B;a'b'c'}^{m_j} \bar{\eta}_j^{m_j} \theta_{\alpha'}^{N_f(a')} \theta_{\beta'}^{N_f(b')} \theta_{\gamma'}^{N_f(c')}, \\ \mathbf{g}_{aa'} &= \delta_{aa'} d\theta_\alpha^{N_f(a)} d\theta_{\alpha'}^{N_f(a')}. \end{aligned} \quad (38)$$

Comparing with usual TPS, here the link indices $\{a, a'\}$ always have definite fermion parity $P_f = \pm 1$. $N_f = 0$ when $P_f = 1$ while $N_f = 1$ when $P_f = -1$.

Let us start from the simplest case with the assumption the environment can also be approximated by some weight. In this case, the imaginary time evolution for GTPS can be reduced to a SVD problem of Grassmann variables. The Grassmann version of the matrix M in Eq.(33) can be constructed as following:

(a) Let us first sum over the bond indices a, a' and integral out the Grassmann variable $\theta_\alpha, \theta_{\alpha'}$:

$$\begin{aligned} \tilde{\mathbf{T}}_{ij;m_i m_j bcb'c'} &= \sum_{aa'} \int \mathbf{g}_{aa'} \tilde{\mathbf{T}}_{abc}^{m_i} \tilde{\mathbf{T}}_{a'b'c'}^{m_j} \\ &= \sum_a \int d\theta_\alpha^{N_f(a)} d\theta_{\alpha'}^{N_f(a')} \tilde{\mathbf{T}}_{A;abc}^{m_i} \bar{\eta}_i^{m_i} \theta_\alpha^{N_f(a)} \theta_\beta^{N_f(b)} \theta_\gamma^{N_f(c)} \tilde{\mathbf{T}}_{B;a'b'c'}^{m_j} \bar{\eta}_j^{m_j} \theta_{\alpha'}^{N_f(a')} \theta_{\beta'}^{N_f(b')} \theta_{\gamma'}^{N_f(c')} \\ &= \sum_a (-)^{[m_i+m_j]N_f(a)} (-)^{m_j[m_i+N_f(b)+N_f(c)]} \tilde{\mathbf{T}}_{A;abc}^{m_i} \tilde{\mathbf{T}}_{B;a'b'c'}^{m_j} \bar{\eta}_i^{m_i} \bar{\eta}_j^{m_j} \theta_\beta^{N_f(b)} \theta_\gamma^{N_f(c)} \theta_{\beta'}^{N_f(b')} \theta_{\gamma'}^{N_f(c')}. \end{aligned} \quad (39)$$

Here the sign factor $(-)^{[m_i+m_j]N_f(a)} (-)^{m_j[m_i+N_f(b)+N_f(c)]}$ comes from the anti-commutating relations of Grassmann variables.

(b) Next we derive the matrix element of the evolution operator under fermion coherent state representation. Let us first calculate them under the usual Fock basis $(c_j^\dagger)^{m_j} (c_i^\dagger)^{m_i} |0\rangle$ with $m_i, m_j = 0, 1$. Let us define:

$$E_{m'_i m'_j}^{m_i m_j} = \langle 0 | (c_i)^{m_i} (c_j)^{m_j} e^{-\delta\tau h_{ij}} (c_j^\dagger)^{m'_j} (c_i^\dagger)^{m'_i} | 0 \rangle \quad (40)$$

Thus, we can expand $e^{-\delta\tau h_{ij}}$ as:

$$e^{-\delta\tau h_{ij}} = \sum_{m_i m_j; m'_i m'_j} E_{m'_i m'_j}^{m_i m_j} (c_j^\dagger)^{m_j} (c_i^\dagger)^{m_i} |0\rangle \langle 0 | (c_i)^{m'_i} (c_j)^{m'_j} \quad (41)$$

In the fermion coherent state basis, we have:

$$\begin{aligned} &\langle \eta'_i, \eta'_j | e^{-\delta\tau h_{ij}} | \eta_i, \eta_j \rangle \\ &= \sum_{m_i m_j; m'_i m'_j} E_{m'_i m'_j}^{m_i m_j} (\bar{\eta}'_j)^{m_j} (\bar{\eta}'_i)^{m_i} (\eta_i)^{m'_i} (\eta_j)^{m'_j} \end{aligned} \quad (42)$$

(c) Then we can evolve the state Ψ to a new state Ψ' :

$$\begin{aligned} \Psi'(\{\bar{\eta}'_i\}, \{\bar{\eta}'_j\}) &= \int d\bar{\eta}_i d\eta_i d\bar{\eta}_j d\eta_j (1 + \eta_i \bar{\eta}_i) (1 + \eta_j \bar{\eta}_j) \\ &\quad \times \langle \eta'_i, \eta'_j | e^{-\delta\tau h_{ij}} | \eta_i, \eta_j \rangle \Psi(\{\bar{\eta}_i\}, \{\bar{\eta}_j\}). \end{aligned} \quad (43)$$

Put Eq.(39) and Eq.(42) into the above equation, it is easy to derive the Grassmann version of the rank 6 tensor T_{ij} defined on the link ij . We have:

$$\begin{aligned}
\tilde{\mathbf{T}}'_{ij;m_i m_j b c b' c'} &= \sum_{m'_i m'_j a} (-)^{[m'_i + m'_j] N_f(a)} (-)^{m'_j [m'_i + N_f(b) + N_f(c)]} E_{m'_i m'_j}^{m_i m_j} \tilde{\mathbf{T}}'_{A;abc}{}^{m'_i} \tilde{\mathbf{T}}'^{m'_j}_{B;ab'c'} (\bar{\eta}'_j)^{m_j} (\bar{\eta}'_i)^{m_i} \theta_{\beta}^{N_f(b)} \theta_{\gamma}^{N_f(c)} \theta_{\beta'}^{N_f(b')} \theta_{\gamma'}^{N_f(c')} \\
&= \sum_{m'_i m'_j a} (-)^{[m'_i + m'_j] N_f(a)} (-)^{m'_j [m'_i + N_f(b) + N_f(c)]} (-)^{m_j [m_i + N_f(b) + N_f(c)]} \\
&\quad \times E_{m'_i m'_j}^{m_i m_j} \tilde{\mathbf{T}}'_{A;abc}{}^{m'_i} \tilde{\mathbf{T}}'^{m'_j}_{B;ab'c'} (\bar{\eta}'_i)^{m_i} \theta_{\beta}^{N_f(b)} \theta_{\gamma}^{N_f(c)} (\bar{\eta}'_j)^{m_j} \theta_{\beta'}^{N_f(b')} \theta_{\gamma'}^{N_f(c')}.
\end{aligned} \tag{44}$$

We notice there is an extra sign factor $(-)^{m_j [m_i + N_f(b) + N_f(c)]}$ after we reorder these Grassmann variables.

(d) Finally, we can define the Grassmann generalization of the M matrix after putting the environment weight for all the inner indices.

$$\begin{aligned}
\mathbf{M}_{bcm_i; b' c' m_j} &= \mathbf{M}_{bcm_i; b' c' m_j} (\bar{\eta}'_i)^{m_i} \theta_{\beta}^{N_f(b)} \theta_{\gamma}^{N_f(c)} \\
&\quad \times (\bar{\eta}'_j)^{m_j} \theta_{\beta'}^{N_f(b')} \theta_{\gamma'}^{N_f(c')}.
\end{aligned} \tag{45}$$

where the coefficient matrix \mathbf{M} reads:

$$\begin{aligned}
\mathbf{M}_{bcm_i; b' c' m_j} &= \sum_{am'_i m'_j} \sqrt{\Lambda_b^y} \sqrt{\Lambda_c^z} \sqrt{\Lambda_{b'}^y} \sqrt{\Lambda_{c'}^z} \\
&\quad \times (-)^{[m'_i + m'_j] N_f(a)} (-)^{m'_j [m'_i + N_f(b) + N_f(c)]} \\
&\quad \times (-)^{m_j [m_i + N_f(b) + N_f(c)]} E_{m'_i m'_j}^{m_i m_j} \tilde{\mathbf{T}}'_{A;abc}{}^{m'_i} \tilde{\mathbf{T}}'^{m'_j}_{B;ab'c'}
\end{aligned} \tag{46}$$

Since h_{ij} is a local fermionic operator, it will always contain even number of fermion operators. As a result, the nonzero elements of \mathbf{M} matrix will always contain even number of Grassmann variables and we can apply GSVD as discussed before. We keep the largest D eigenvalues:

$$\mathbf{M}_{bcm_i; b' c' m_j} = \sum_a U_{bcm_i; a} \Lambda'_a V_{b' c' m_j; a} \tag{47}$$

The coefficient matrix M will have a block diagonalize structure, hence the new index a will have a definite fermion parity $P_f(a) = P_f(b)P_f(c) = P_f(b')P_f(c')$.

Similar as in usual TPS case, the new Grassmann tensors $\tilde{\mathbf{T}}'_i$ and $\tilde{\mathbf{T}}'_j$ have the form

$$\begin{aligned}
\tilde{\mathbf{T}}'^{m_i}_{A;abc} &= \frac{\sqrt{\Lambda'_a}}{\sqrt{\Lambda_b^y} \sqrt{\Lambda_c^z}} U_{bcm_i; a} \theta_{\alpha}^{N_f(a)} (\bar{\eta}'_i)^{m_i} \theta_{\beta}^{N_f(b)} \theta_{\gamma}^{N_f(c)} \\
&= \tilde{\mathbf{T}}'^{m_i}_{A;abc} (\bar{\eta}'_i)^{m_i} \theta_{\alpha}^{N_f(a)} \theta_{\beta}^{N_f(b)} \theta_{\gamma}^{N_f(c)} \\
\tilde{\mathbf{T}}'^{m_j}_{B;a'b'c'} &= \frac{\sqrt{\Lambda'_{a'}}}{\sqrt{\Lambda_{b'}^y} \sqrt{\Lambda_{c'}^z}} V_{b' c' m_j; a'} \theta_{\alpha'}^{N_f(a')} (\bar{\eta}'_j)^{m_j} \theta_{\beta'}^{N_f(b')} \theta_{\gamma'}^{N_f(c')} \\
&= \tilde{\mathbf{T}}'^{m_j}_{B;a'b'c'} (\bar{\eta}'_j)^{m_j} \theta_{\alpha'}^{N_f(a')} \theta_{\beta'}^{N_f(b')} \theta_{\gamma'}^{N_f(c')}
\end{aligned} \tag{48}$$

However, due to the reordering of Grassmann vari-

ables, extra signs appear in the new tensors $\tilde{\mathbf{T}}'_A$ and $\tilde{\mathbf{T}}'_B$.

$$\begin{aligned}
\tilde{\mathbf{T}}'^{m_i}_{A;abc} &= (-)^{m_i N_f(a)} \frac{\sqrt{\Lambda'_a}}{\sqrt{\Lambda_b^y} \sqrt{\Lambda_c^z}} U_{bcm_i; a} \\
\tilde{\mathbf{T}}'^{m_j}_{B;a'b'c'} &= (-)^{m_j N_f(a')} \frac{\sqrt{\Lambda'_{a'}}}{\sqrt{\Lambda_{b'}^y} \sqrt{\Lambda_{c'}^z}} V_{b' c' m_j; a'}
\end{aligned} \tag{49}$$

Again Λ'_a is used as the new environment weight for all links along x direction.

The full environment tensors can be very similar as in usual TPS case. The Grassmann version of the environment tensor ρ can be efficiently simulated by GTPS. The environment tensor e can be calculated from ρ and $\tilde{\mathbf{T}}'_{ij}$. The cost function can be derived from Eq.(28) after replacing ρ, e and T to their Grassmann version. After we contract the tensor-net and integral out all the Grassmann variables, it can be reduced to a usual multi-variable quadratic minimization problem for the coefficient tensors $\tilde{\mathbf{T}}'_A$ and $\tilde{\mathbf{T}}'_B$, we can solve it by using the sweep method. Although the algorithm with full environment is general, it is still very time consuming and a much more efficient method is very desired. Nevertheless, it turns out that the simple updated method works very well in many cases and we will focus on the application of this method in this paper.

C. A free fermion example

In this subsection, we demonstrate the above algorithm by studying a free fermion model on honeycomb lattice. We consider the following (spinless) fermion Hamiltonian:

$$H = -\Delta \sum_{\langle ij \rangle} (c_i^\dagger c_j^\dagger + h.c.) + \mu \sum_i n_i \tag{50}$$

We first test our algorithm in the parameter region where the system opens a gap. For example, we can fix $\mu = 1$ and take different values for Δ from 0.1 to 0.5. See in Fig. (10), even with the minimal inner dimension $D = 2$, the GTPS variational approach already gives out very good ground state energy. Here and through out the whole paper, we fix the total system size to be $N = 2 \times 3^6$ sites and with PBC. (The GTEG algorithm will allow us to reach huge size in principle, however, for better convergency, we choose relatively large but not huge size.)

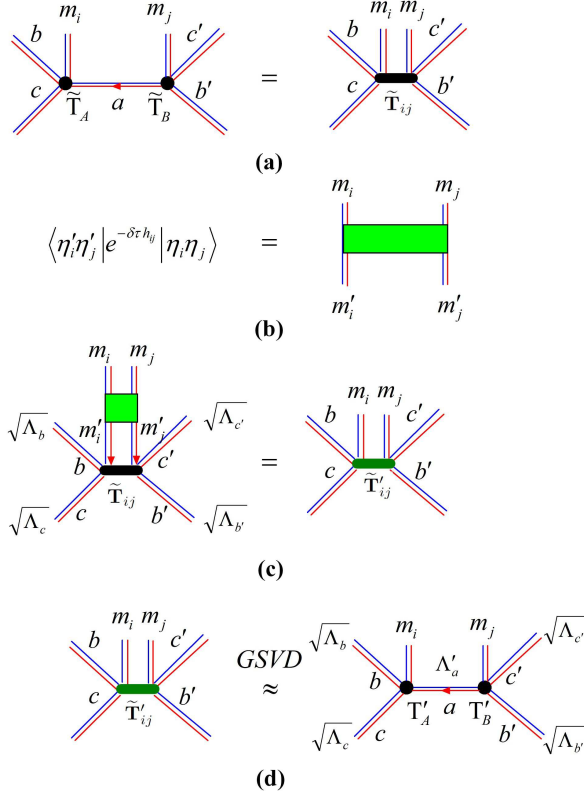


FIG. 8: A graphic representation for the simplified imaginary time evolution algorithm for Grassmann tensor product states. In step (a), we sum over the inner indices and integral out the Grassmann variables on the shared link for two adjoint Grassmann tensors $\tilde{\mathbf{T}}_A$ and $\tilde{\mathbf{T}}_B$. In step (b), we express the two sites evolution operator $e^{-\delta\tau h_{ij}}$ under fermion coherent basis. In step (c) and (d), we apply the evolution operator $e^{-\delta\tau h_{ij}}$ to the two sites Grassmann tensor $\tilde{\mathbf{T}}_{ij}$ and derive a new two sites Grassmann tensor $\tilde{\mathbf{T}}'_{ij}$. Then we approximate it by two new adjoint Grassmann tensors $\tilde{\mathbf{T}}'_A$ and $\tilde{\mathbf{T}}'_B$ with respect to the environment weights Λ . We also use double lines to label different fermion parities for the physical indices. For the simple spinless fermion example, red line represents one fermion state and blue line represents non fermion state. The metric $(1 + \eta_i \bar{\eta}_i)$ is the standard metric for the physical indices.

We note the agreement for the ground state energy is better for small Δ , which is expected since the system becomes a trivial vacuum state $|0\rangle$ in the limit $\Delta = 0$. In the insert of Fig. 10, we also plot the ground energy as a function of D_{cut} and it is shown the energy converges for very small D_{cut} (around $D_{cut} = 15$, where D_{cut} is the number of singular value we keep in the GTERG algorithm). We find the relative error can be very small, e.g., 0.4% for $\Delta = 0.2$.

Although we get good results for the above simple example, it is not quite surprising since a trivial gapped fermion system only evolves local physics. A much more challenging and interesting example is at $\mu = 0$, in which

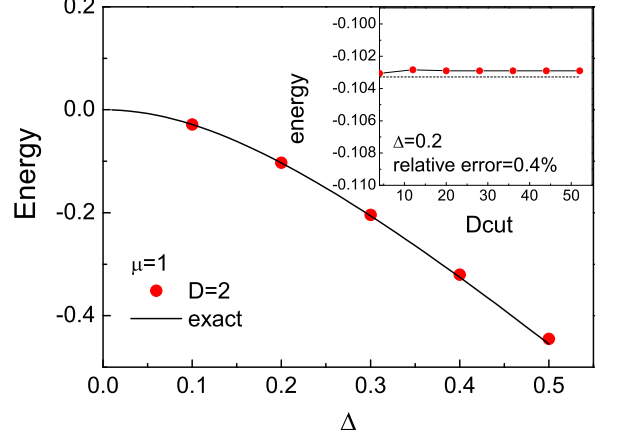


FIG. 9: Ground state energy as a function of Δ for fixed $\mu = 1$. As a bench mark, we also plot the exact energy of the free fermion Hamiltonian. Insert: Relative error of ground state energy as a function of D_{cut} for $\Delta = 0.2$. D_{cut} is the number of singular values kept in the Grassmann SVD decomposition¹⁷.

case the low energy physics of the system is described by two Dirac cones in the first Brillouin Zone (BZ). Actually, up to a particle-hole transformation on one sublattice, the above fermion pairing Hamiltonian is equivalent to the fermion hopping Hamiltonian that describes the novel physics in graphene (the spinless version) where low energy electrons deserve a Dirac like dispersion. In Fig. 10, we plot the ground state energy as a function of D_{cut} for inner dimensions $D = 2$ and $D = 4$. In this case, the $D = 2$ approach only gives very poor results comparing to the gapped case. However, when we increase the inner dimension to $D = 4$, we find that the ground state energy agrees pretty well with the exact one, with a relative error of 0.6%. Another interesting feature is that such a critical system would require a much larger D_{cut} (around $D_{cut} = 70$ for $D = 4$.) for the convergence of the GTERG algorithm. Later, we would discuss a possible improvement for the GTERG algorithm, which allows us to access much larger inner dimension D .

Finally, we would like to make some comments and discussions about the above results:

(a) Although a gapless fermion system with Dirac cones is critical, it does not violate the area law because it only contains zero dimensional Fermi surfaces.

(b) The good agreement in ground state energy does not imply the good agreement in long range correlations. Indeed, our conjecture is that for any finite D , the variational wave function we derive may be always associated with a finite correlation length which scales polynomially in D . We note that an interesting critical fPEPS state with finite inner dimension $D = 2$ was proposed in Ref.¹⁸, however, that model is different from our case since the

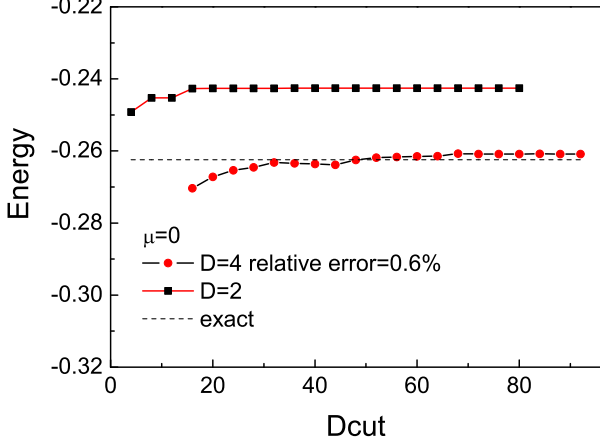


FIG. 10: Ground state energy as a function of D_{cut} for fixed $\mu = 0$. As a bench mark, we also plot the exact energy of the corresponding free fermion Hamiltonian.

Dirac cones in that model contain a quadratic dispersion along some directions in the first BZ.

(c) Although the GTPS variational approach can not describe the above system with finite inner dimension D , the variational results will still be very useful. From the numerical side, we can apply both finite D and finite size scalings to estimate the physical quantities in the infinite D and infinite size limit. From the analytic side, the finite correlation length corresponds to a finite gap in the system, which is known as Dirac mass term in the effective theory³⁶. In quantum field theory, a controlled calculation (without singularities in calculating correlation functions) can be performed by first taking the Dirac mass term to be finite and then pushing it to the zero limit.

IV. POSSIBLE IMPROVEMENTS OF THE TERG APPROACH

In this section, we will discuss possible improvements for the TERG algorithm and its Grassmann generalization. Again, let us start from usual TPS case. Its Grassmann generalization would be straightforward by replacing the complex number valued tensors with those Grassmann valued tensors. We notice the simple SVD method used in TERG algorithm actually implies the following cost function:

$$f_{\text{SVD}} = \|\mathbb{T} - \mathbb{S} \cdot \mathbb{S}'\|, \quad (51)$$

where the rank four double tensor \mathbb{T} is defined as $\mathbb{T}_A \cdot \mathbb{T}_B$ and \cdot means summing over indices for the connected link, as see in Fig.11 (a). (Actually it is the inner product of two vectors if we interpolate $\mathbb{T}_{A(B)}$ as D^6 dimensional vectors, where D is the inner dimension of the TPS.) $\|\cdots\|$ is the usual 2-norm of a vector. (The rank 4 tensor \mathbb{T} and rank

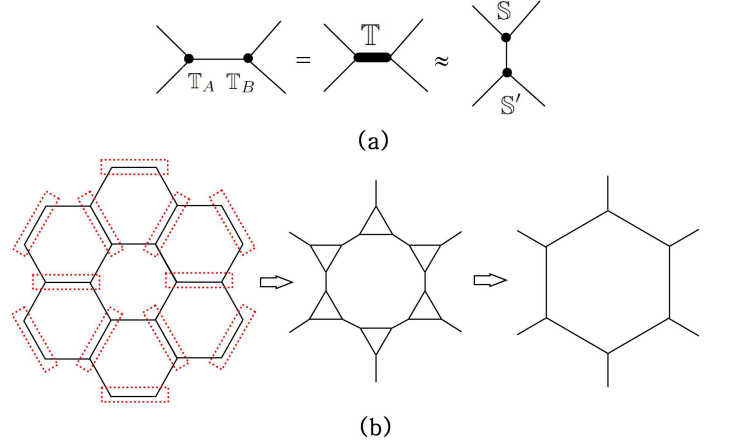


FIG. 11: (a) A graphic representation for $\mathbb{T} = \mathbb{T}_A \cdot \mathbb{T}_B$ and $\mathbb{T} \sim \mathbb{S} \cdot \mathbb{S}'$. The symbol \cdot here means sum over the indices for the shared link for two connected tensors. (b) A schematic plot for the TERG scheme on honeycomb lattice. The first step is approximate while the second step is exact.

3 tensors \mathbb{S}, \mathbb{S}' can be viewed as D^8 and D^6 dimensional vectors.) Such a cost function only minimizes the 2-norm of local error $\delta\mathbb{T} = \mathbb{T} - \mathbb{S} \cdot \mathbb{S}'$ for a given cut-off dimension D_{cut} (the dimensional of the link shared by \mathbb{S} and \mathbb{S}') and could not be the optimal one for minimizing global error. To figure out the optimal cost function, let us divide the system into large patches, as seen in Fig.12. If we trace out all the internal indices inside the patch, we can derive a rank L (L is the number of sites on the boundary of the patch) tensor \mathbb{T}' for the patch and the norm of TPS can be represented as the tensor trace of the new double tensors \mathbb{T}' . When we perform the TERG algorithm and replace \mathbb{T} by $\mathbb{S} \cdot \mathbb{S}'$, we aim at making a small error for the double tensor \mathbb{T}' .

Now it is clear why the simple SVD method that minimizes local errors could not approximate the patch double tensor \mathbb{T}' in an optimal way. Let us rewrite \mathbb{T}' as $\mathbb{T}' = \mathbb{E} \cdot \mathbb{T}$. (Notice here we regard the rank L double tensor \mathbb{T}' as a D^{2L} dimensional vector, the rank 4 double tensor \mathbb{T} as a D^8 dimensional vector and the rank $L+4$ double tensor \mathbb{E} as a D^{2L} by D^8 matrix.) The double tensor \mathbb{E} is called as environment tensor. The cost function which provides the best approximation for \mathbb{T}' can be represented as:

$$f = \|\mathbb{E} \cdot (\mathbb{T} - \mathbb{S} \cdot \mathbb{S}')\| \quad (52)$$

Again, \cdot means the vector inner product and $\|\cdots\|$ means the usual 2-norm. Comparing with the simple SVD method, the environment tensor gives a complex weight for each component of the local error $\delta\mathbb{T}$. Notice the cost function proposed here is very different from the one in Ref.³², which aims at minimizing $\text{Tr}(\mathbb{E} \cdot \mathbb{T})$.

Although the environment tensor \mathbb{E} is conceptually useful, it is impossible to compute this rank $L+4$ tensor when the patch size becomes very large. Nevertheless, we

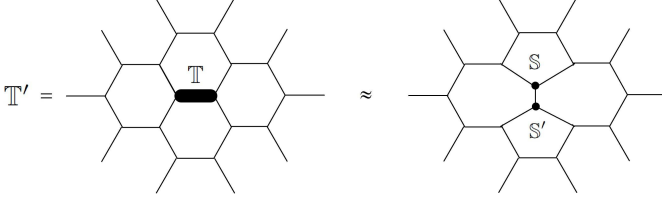


FIG. 12: A schematic plot for the patch double tensor \mathbb{T}' . The global cost function aims at finding the best way to minimize the error for the above patch double tensor.

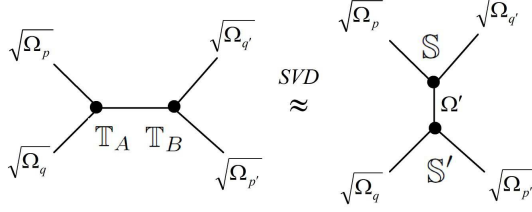


FIG. 13: A graphic representation for the first step of the weighted TERG algorithm.

can derive a simplified environment through the simplified time evolution algorithm. The key step is also based on the conjecture that the rank 8 tensor $\mathbb{E}^\dagger \cdot \mathbb{E}$ can be factorized into a product form:

$$(\mathbb{E}^\dagger \cdot \mathbb{E})_{pq p' q'; \bar{p} \bar{q} \bar{p}' \bar{q}'} = \Omega_p^y \Omega_q^z \Omega_{p'}^y \Omega_{q'}^z \delta_{p \bar{p}} \delta_{q \bar{q}} \delta_{p' \bar{p}'} \delta_{q' \bar{q}'}, \quad (53)$$

where $p = (b, \bar{b}), q = (c, \bar{c})$ are the double indices. For any converged T_A and T_B from the simplified time evolution algorithm with converged weight vectors $\Lambda^{* \alpha}$, the weight vectors Ω^α for double tensors \mathbb{T} can be determined as:

$$\Omega_p^y = \Lambda_b^{* y} \Lambda_{\bar{b}}^{* y}, \Omega_q^z = \Lambda_c^{* z} \Lambda_{\bar{c}}^{* z}. \quad (54)$$

The above conjecture for the environment is reasonable when the environment of T^m can be approximated as a product form since $\mathbb{T} = \sum_m \bar{T}^m \otimes T^m$

Similar as the simplified time evolution algorithm, solving the optimal cost function in this case can be implemented by the SVD decomposition for matrix \mathbb{M} :

$$\begin{aligned} \mathbb{M}_{q' p; q p'} &= \mathbb{T}_{p q p' q'} \sqrt{\Omega_p} \sqrt{\Omega_q} \sqrt{\Omega_{p'}} \sqrt{\Omega_{q'}} \\ &\simeq \sum_{r=1}^{D_{cut}} U_{q' p; r} V_{q p'; r} \Omega'_r \end{aligned} \quad (55)$$

Then the rank 3 double tensors \mathbb{S} and \mathbb{S}' can be determined as:

$$\begin{aligned} \mathbb{S}_{r q' p} &= \frac{\sqrt{\Omega'_r}}{\sqrt{\Omega_{q'}} \sqrt{\Omega_p}} U_{q' p; r} \\ \mathbb{S}'_{r' q p'} &= \frac{\sqrt{\Omega'_{r'}}}{\sqrt{\Omega_q} \sqrt{\Omega_{p'}}} V_{q p'; r'} \end{aligned} \quad (56)$$

Finally, the weight vector Ω^x for $x-link$ can be updated as $\Omega^x = \Omega'$.

In general cases, the assumption Eq.(53) could not be true, however, as long as $\mathbb{E}_{\lambda; p q p' q'} / \sqrt{\Omega_p} \sqrt{\Omega_q} \sqrt{\Omega_{p'}} \sqrt{\Omega_{q'}}$ has a much more uniform distribution (up to proper normalization):

$$\left| \frac{\mathbb{E}_{\lambda; p q p' q'}}{\sqrt{\Omega_p} \sqrt{\Omega_q} \sqrt{\Omega_{p'}} \sqrt{\Omega_{q'}}} \right| \sim 1, \quad (57)$$

the above weighted TERG(wTERG) algorithm can still improve the accuracy for fixed D_{cut} with the same cost. This is because the SVD method is the best truncation method if the environment has a random but uniform distribution.

By replacing the complex valued double tensors with Grassmann variable valued double tensors, all the above discussions will be valid for GTPS. However, the definition of the inner product \cdot and the corresponding 2-norm $\|\dots\|$ should also be generalized into their Grassmann version, which evolves the integration over Grassmann variables for the connected links with respect to the standard Grassmann metric. For example, the cost function of the GSVD method discussed in Ref.¹ can be formally written as:

$$f_{\text{GSVD}} = \delta \mathbb{T}^f \cdot \delta \mathbb{T}^{f \dagger} = \|\delta \mathbb{T}^f\| = \|\mathbb{T}^f - \mathbb{S}^f \cdot \mathbb{S}'^f\|, \quad (58)$$

To explain the meaning of the above expression more explicitly, we consider a simple case that \mathbb{T}^f only contains one species of Grassmann variables. We can express \mathbb{T}^f as:

$$\mathbb{T}_{p q p' q'}^f = \mathbb{T}_{p q p' q'} (\theta_\beta)^{N_f(p)} (\theta_\gamma)^{N_f(q)} (\theta_{\beta'})^{N_f(p')} (\theta_{\gamma'})^{N_f(q')}, \quad (59)$$

where $\mathbb{T}_{p q p' q'}$ is the complex coefficient of the Grassmann number valued double tensor $\mathbb{T}_{p q p' q'}^f$ and $N_f(p) = \frac{P_f(p)+1}{2}$ is determined by the fermion parity of the inner index p . We notice $\mathbb{T}_{p q p' q'} = \sum_r \mathbb{T}_{A; r p q} \mathbb{T}_{B; r p' q'}$ if we express the Grassmann number valued double tensors $\mathbb{T}_{A(B); r p q}^f$ on sublattice $A(B)$ as:

$$\mathbb{T}_{A(B); r p q}^f = \mathbb{T}_{A(B); r p q} (\theta_\alpha)^{N_f(r)} (\theta_\beta)^{N_f(p)} (\theta_\gamma)^{N_f(q)} \quad (60)$$

Similarly, we can express \mathbb{S}^f and \mathbb{S}'^f as:

$$\begin{aligned} \mathbb{S}_{r q' p}^f &= \mathbb{S}_{r q' p} (\theta_\alpha)^{N_f(r)} (\theta_{\gamma'})^{N_f(q')} (\theta_\beta)^{N_f(p)} \\ \mathbb{S}'_{r' q p'}^f &= \mathbb{S}'_{r' q p'} (\theta_{\alpha'})^{N_f(r')} (\theta_\gamma)^{N_f(q)} (\theta_{\beta'})^{N_f(p')} \end{aligned} \quad (61)$$

Again, $\mathbb{S}_{r q' p}$ and $\mathbb{S}'_{r' q p'}$ are the complex valued coefficients. Recall the definition of the standard Grassmann metric $\mathbf{g}_{rr'}$:

$$\mathbf{g}_{rr'} = \delta_{rr'} (d\theta_\alpha)^{N_f(r)} (d\theta_{\alpha'})^{N_f(r')}, \quad (62)$$

the inner product $\mathbb{S}^f \cdot \mathbb{S}'^f$ explicitly means:

$$\begin{aligned}
(\mathbb{S}^f \cdot \mathbb{S}'^f)_{pp'q'q'} &= \sum_{rr'} \int \mathbf{g}_{rr'} \mathbb{S}_{rq'p} \mathbb{S}'_{r'qp'} (\theta_\alpha)^{N_f(r)} (\theta_{\gamma'})^{N_f(q')} (\theta_\beta)^{N_f(p)} (\theta_{\alpha'})^{N_f(r')} (\theta_\gamma)^{N_f(q)} (\theta_{\beta'})^{N_f(p')} \\
&= \sum_r \mathbb{S}_{rq'p} \mathbb{S}'_{r'qp'} (\theta_{\gamma'})^{N_f(q')} (\theta_\beta)^{N_f(p)} (\theta_\gamma)^{N_f(q)} (\theta_{\beta'})^{N_f(p')}.
\end{aligned} \tag{63}$$

Thus, we have:

$$\delta \mathbb{T}_{pp'q'q'}^f = \delta \mathbb{T}_{pp'q'q'} (\theta_{\gamma'})^{N_f(q')} (\theta_\beta)^{N_f(p)} (\theta_\gamma)^{N_f(q)} (\theta_{\beta'})^{N_f(p')}, \tag{64}$$

with

$$\begin{aligned}
\delta \mathbb{T}_{pp'q'q'} &= \mathbb{T}_{pp'q'q'} (-)^{N_f(p')} - \sum_r \mathbb{S}_{rq'p} \mathbb{S}'_{rqp'} \\
&= \mathbb{T}'_{pp'q'q'} - \sum_r \mathbb{S}_{rq'p} \mathbb{S}'_{rqp'}
\end{aligned} \tag{65}$$

Now it is clear that up to a sign twist, the GSVD cost function is equivalent to the cost function of its complex coefficient tensors:

$$f_{GSVD} = \|\delta \mathbb{T}^f\| = \|\delta \mathbb{T}\| = \|\mathbb{T}' - \mathbb{S} \cdot \mathbb{S}'\| \tag{66}$$

Explicitly the same as in the TERG case, the best approximation for a given D_{cut} is nothing but the SVD decomposition for the coefficient tensor \mathbb{T}' . (If we view $\mathbb{T}'_{pp'q'q'}$ as a matrix $\mathbb{M}_{q'p;q'p'} = \mathbb{T}'_{pp'q'q'} \simeq \sum_{r=1}^{D_{cut}} \mathbb{S}_{rp'q} \mathbb{S}'_{rqp'}$.) On the other hand, as already having been discussed in Ref.¹, the constraint Eq. (5) of GTPS implies their double tensors containing even number of Grassmann number. As a result, \mathbb{M} is block diagonalized and the index r will have a definite parity $P^f(r) = P^f(p)P^f(q) = P^f(p')P^f(q')$. We notice the novel sign factor $(-)^{N_f(p')}$ here arises from the anti-commuting nature of the Grassmann variables and will encode the fermion statistics. The second RG step remains the same as in GTERG and a similar novel sign factor will also emerge there.

All the above discussion will still be correct if the inner index of the double tensor \mathbb{T}^f contain multiple species of Grassmann variables. Indeed, starting from the standard GTPS, the double tensor \mathbb{T}^f in the first RG step will contain two species of Grassmann variables. This is because $\mathbb{T}_{A(B)}^f = \sum_m \bar{\mathbf{T}}_{A(B)}^m \otimes \mathbf{T}_{A(B)}^m$ and $\mathbb{T}^f = \mathbb{T}_A^f \cdot \mathbb{T}_B^f$. In the second and later RG steps, $\mathbb{T}_{A(B)}^f$ will only contain one specie of Grassman variables.

The discussion for the environment effect will be in a similar fashion. Especially, if we use some weighting factor to approximate the environment effect, the coefficient tensors \mathbb{S}, \mathbb{S}' will take the same form as in usual TPS case. However, an important sign factor should be included when we define the matrix \mathbb{M} . Again, the environment weight for the first step is determined by the time evolution algorithm of GTPS. Same as in the bosonic case, the

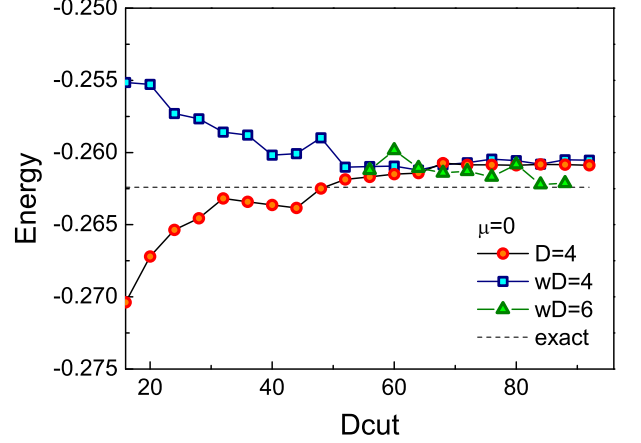


FIG. 14: A comparison of the ground state energy as function of D_{cut} at $\mu = 0$. By introducing the environment weight in the GTERG method, an important improvement is that the ground state energy is always above the exact value, which is very important for variational approach

singular value obtained from the GSVD would perform as the environment weight for next RG step.

In Fig. 14, we implement the above algorithm to the free fermion Hamiltonian Eq.(50) at critical point ($\mu = 0$). We see an important improvement that the ground state energy decreases when increasing D_{cut} and is strictly above the exact energy, unlike the simple GTERG approach, which can overestimate the ground state energy for small D_{cut} . However, for larger enough D_{cut} , the two approaches converge to the same values, as expected. We further use the new algorithm to study the critical model with larger inner dimension D . Up to $D = 6$, we find that the ground state energy from the GTPS approach is almost the same as the exact one (relative error $\sim 0.1\%$).

V. SUMMARY

In this paper, we first derive a standard form of GTPS that only contains one specie of Grassmann variable for each inner index and significantly simplifies the representations in our numerical calculations. Based on the fermion coherent state representation, we further general-

ize the imaginary time evolution algorithms into fermion systems. We study a simple free fermion example on honeycomb lattice, including both off-critical and critical cases to test our new algorithms. Finally, we discuss the importance of the environment effect of the TERG/GTERG method and present a simple improvement by introducing proper environment weights.

Although the simple time evolution algorithm discussed here is not generic enough, it has already allowed us to study many interesting and important models, such as Hubbard/ $t - J$ model, whose ground state is believed to be a superconductor. The evidence for the existence of superconductivity in these models based on the GTPS algorithm will be discussed and bench marked with other methods elsewhere³⁷. Of course, the generic algorithm is also very important and desired, especially for those systems with topological order. Actually, the general dis-

cussion in section II have already made some progress along this direction, but not efficient and stable enough at this stage.

On the other hand, further improving the efficiency of contacting (Grassmann) tensor net is also very important. Although the GTERG/TERG algorithm provides us promising results in many cases, it is still not efficient enough since the algorithm is not easy to be parallelized. Recently, a novel idea of combination the concept of renormalization and Monte Carlo(MC)³⁴ has made great success for boson/spin systems, it would be very natural to generalize it into fermion/electron systems based on the Grassmann variable representations.

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